# Graph burning and non-uniform *k*-centers for small treewidth

#### Matej Lieskovský and Jiří Sgall

Charles University, Prague

Aussois, May 2022











#### Definition: Graph burning

[Bonato et al. 2015]

- Input: Graph G = (V, E)
- Output: Vertices u<sub>1</sub>,..., u<sub>g</sub> ∈ V, so that for each v ∈ V there exists i with d(v, u<sub>i</sub>) ≤ g − i − 1
- Objective: Minimize g

#### Definition: k-center

#### [Hakimi 1964]

- Input: Graph G = (V, E), k
- Output: Vertices u<sub>1</sub>,..., u<sub>k</sub> ∈ V, and r so that for each v ∈ V exist an i with d(v, u<sub>i</sub>) ≤ r
- Objective: Minimize r

#### Definition: k-center

#### • Input: Graph G = (V, E), k

- Output: Vertices u<sub>1</sub>,..., u<sub>k</sub> ∈ V, and r so that for each v ∈ V exist an i with d(v, u<sub>i</sub>) ≤ r
- Objective: Minimize r

#### Definition: Non-uniform k-center

#### [Chakrabarty et al. 2020]

[Hakimi 1964]

- Input: Graph G = (V, E), k, radii  $r_1, \ldots, r_k$
- Output: Vertices u<sub>1</sub>,..., u<sub>k</sub> ∈ V, so that for each v ∈ V exist an i with d(v, u<sub>i</sub>) ≤ r<sub>i</sub>
- Objective: Test feasibility

#### Definition: Non-uniform k-center

- Input: Graph G = (V, E), k, radii  $r_1, \ldots, r_k$
- Output: Vertices  $u_1, \ldots, u_k \in V$ , so that for each  $v \in V$  exist an *i* with  $d(v, u_i) \leq r_i$



## Paths and linear forests



The problems Trees Treewidth General graphs

## Paths and linear forests



For sets of disjoint paths, Graph burning

- is NP-hard, and
- has a PTAS.

[Bessy *et al.* 2017] [Bonato, Kamali 2019]

## Paths and linear forests



For sets of disjoint paths, Graph burning

- is NP-hard, and
- has a PTAS.

[Bessy *et al.* 2017] [Bonato, Kamali 2019]

## Our results

#### Graph burning

PTAS for trees and graphs of bounded treewidth.

## Our results

#### Graph burning

PTAS for trees and graphs of bounded treewidth.

#### Non-uniform k-center

XP algorithm parametrized by both the number of distinct radii and treewidth.

### Our results

#### Graph burning

PTAS for trees and graphs of bounded treewidth.

#### Non-uniform k-center

XP algorithm parametrized by both the number of distinct radii and treewidth.

Reduction:

Use radii  $\varepsilon \cdot g$ ,  $2\varepsilon \cdot g$ , ..., with  $\varepsilon \cdot g$  centers using each one.

# Algorithm for trees

#### Dynamic programming over a tree

Process the tree bottom up.

For each vertex, remember the set of possible configurations each containing:

- The number of centers of each type used in the subtree
- The maximal coverage that can be achieved, which is
  - either +*a*: the centers in the subtree can cover nodes up to the distance *a* from the processed vertex
  - or -a: some nodes in the subtree up to the distance a from the processed vertex need to be covered by a center outside of the tree

# Algorithm for trees

#### Dynamic programming over a tree

Process the tree bottom up.

For each vertex, remember the set of possible configurations each containing:

- The number of centers of each type used in the subtree
- The maximal coverage that can be achieved, which is
  - either +*a*: the centers in the subtree can cover nodes up to the distance *a* from the processed vertex
  - or -a: some nodes in the subtree up to the distance a from the processed vertex need to be covered by a center outside of the tree

Can be generalized to arbitrary edge lengths

The problems Trees Treewidth General graphs

# Treewidth: Introduction



#### Definition of treewidth

- A tree decomposition of G is a tree of bags such that
  - each bag contains a subgraph of G,
  - each edge appears in some bag, and
  - each vertex is contained in a connected subset of bags.

The treewidth is the maximal number of vertices in a bag, minus 1.

The problems Trees Treewidth General graphs

# Treewidth: Introduction



#### Definition of treewidth

- A tree decomposition of G is a tree of bags such that
  - each bag contains a subgraph of G,
  - each edge appears in some bag, and
  - each vertex is contained in a connected subset of bags.

The treewidth is the maximal number of vertices in a bag, minus 1.

# Algorithm for bounded treewidth

#### Tidy decompositions

If a vertex v is covered by a center at u, any vertex on any shortest path from v to u is also covered by the same center.

# Algorithm for bounded treewidth

#### Tidy decompositions

If a vertex v is covered by a center at u, any vertex on any shortest path from v to u is also covered by the same center.

#### Dynamic programming over a tree of bags

Process the tree bottom up.

For each bag, remember the set of possible configurations each containing:

- The number of centers of each type used in the already processed subtree
- For each vertex in the bag, the center serving this vertex

# Algorithm for bounded treewidth

#### Tidy decompositions

If a vertex v is covered by a center at u, any vertex on any shortest path from v to u is also covered by the same center.

#### Dynamic programming over a tree of bags

Process the tree bottom up.

For each bag, remember the set of possible configurations each containing:

- The number of centers of each type used in the already processed subtree
- For each vertex in the bag, the center serving this vertex

Tidy decompositions can be verified locally on each edge.

#### *k*-center

[Hochbaum, Shmoys 1985]

2-approximation, this is optimal.

#### k-center

[Hochbaum, Shmoys 1985]

2-approximation, this is optimal.

Greedy algorithm: Greedily pick vertices with distances > 2r from each other.

- If at most k vertices picked, these are centers with radius 2r.
- If > k vertices found, each of them needs a different center of radius r, so it is not a feasible instance.

#### k-center

[Hochbaum, Shmoys 1985]

2-approximation, this is optimal.

Greedy algorithm: Greedily pick vertices with distances > 2r from each other.

- If at most k vertices picked, these are centers with radius 2r.
- If > k vertices found, each of them needs a different center of radius r, so it is not a feasible instance.

#### Non-uniform *k*-center with two radii [Chakrabarty *et al.* 2020]

- 2-approximation if one radius is 0 (aka "outliers")
- $(1 + \sqrt{2})$ -approximation otherwise

#### Greedy algorithm is a 3-approximation

[Bessy et al. 2017]

Pick vertices greedily with distances > 2g from each other

- If at most g vertices picked, these centers burn the graph in time 3g.
- If > g vertices found, each of them needs a different center of radius ≤ g, so it is not a feasible instance.

#### Open problem

Find a better approximation for general graphs.